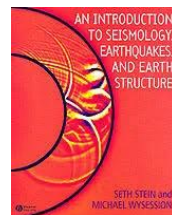




GEO-DEEP 9300: Introduction to receiver functions

Valerie Maupin

Many figures from IRIS training school lecture from Anne Sheehan (2006)
and from Stein and Wyession:



Receiver functions: «RFs»

Goal : detect interfaces in the subsurface

Reflection seismics:

Figure 1.1-5: Demonstration of the seismic reflection method.

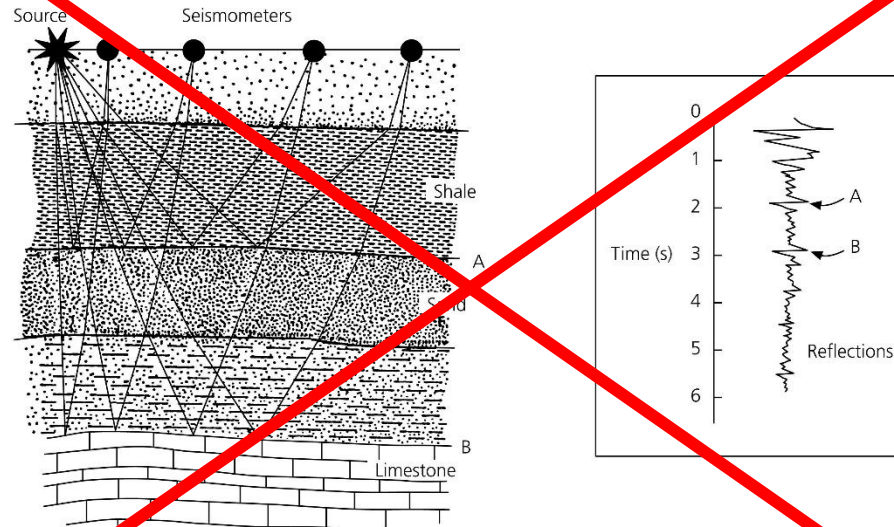
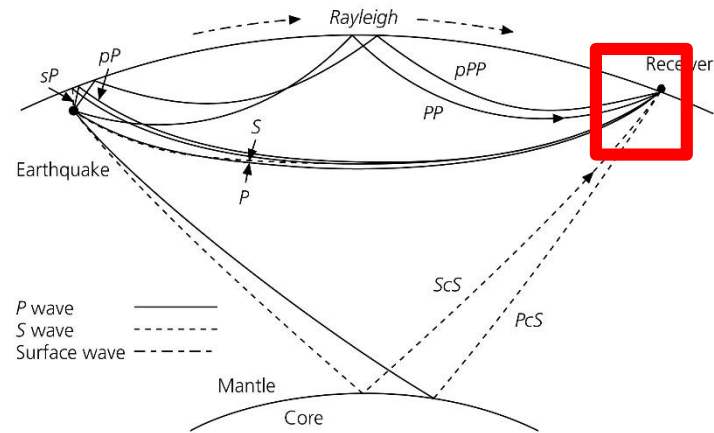
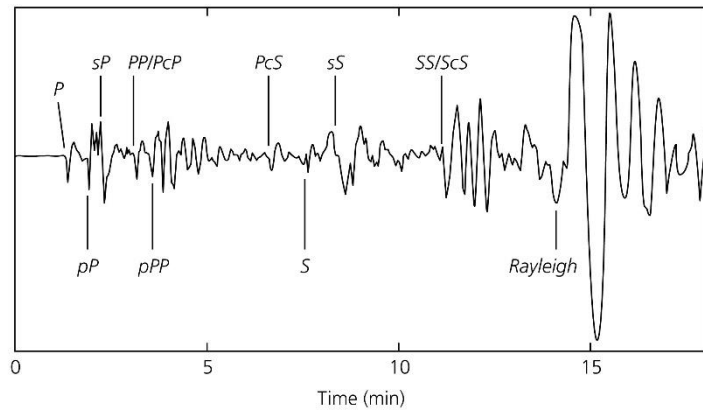
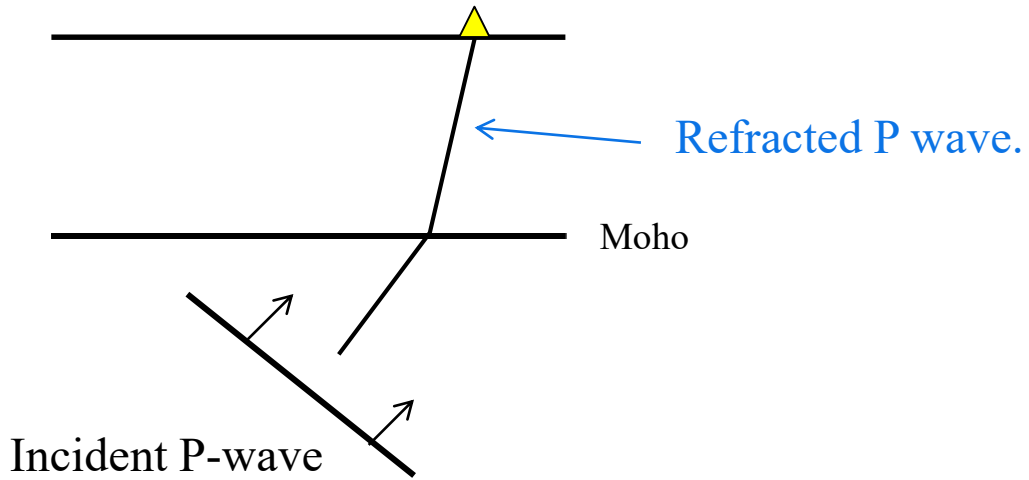


Figure 1.1-3: Example of seismogram, showing accompanying ray paths.





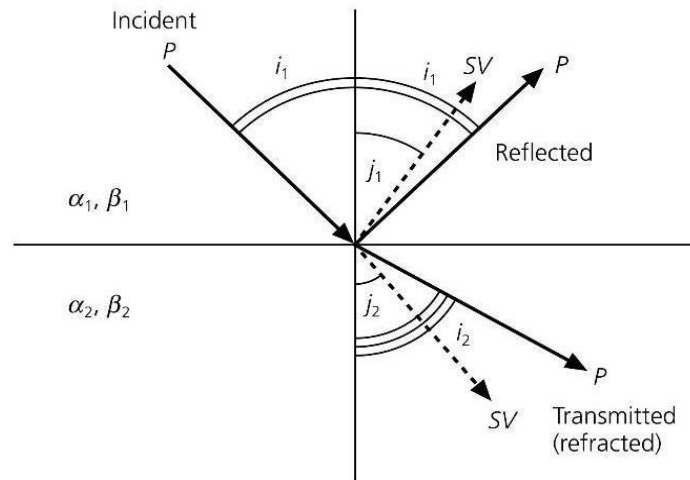
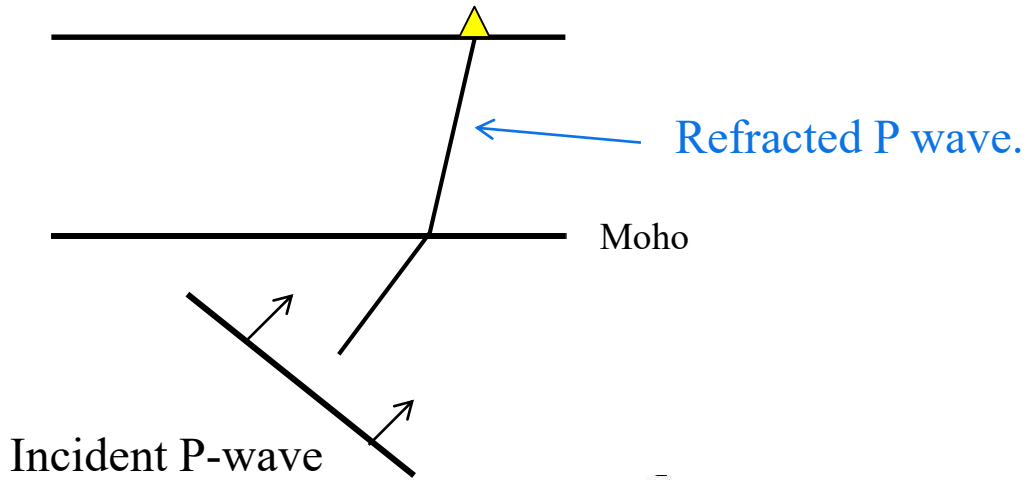
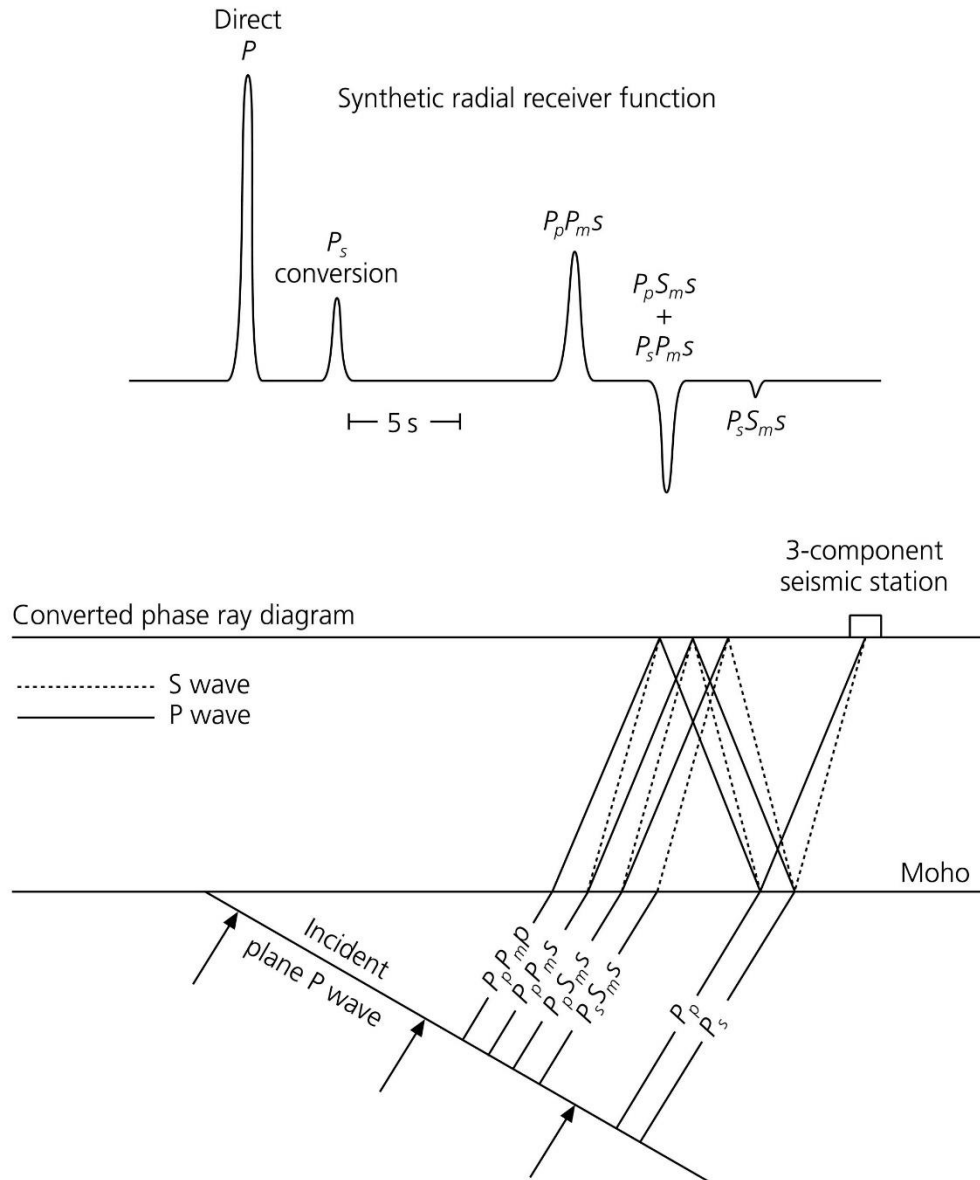
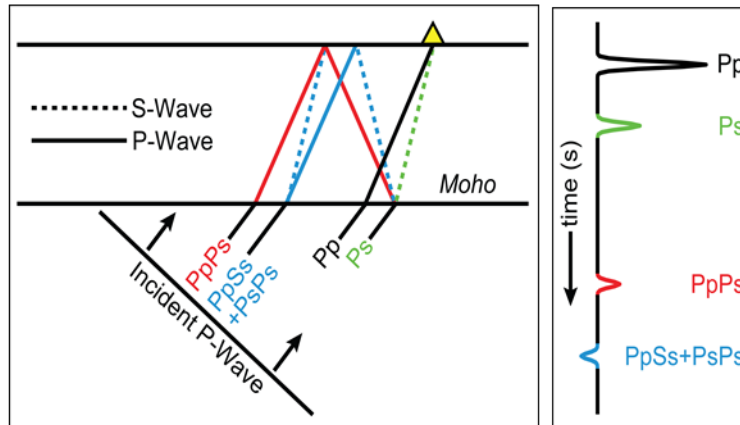
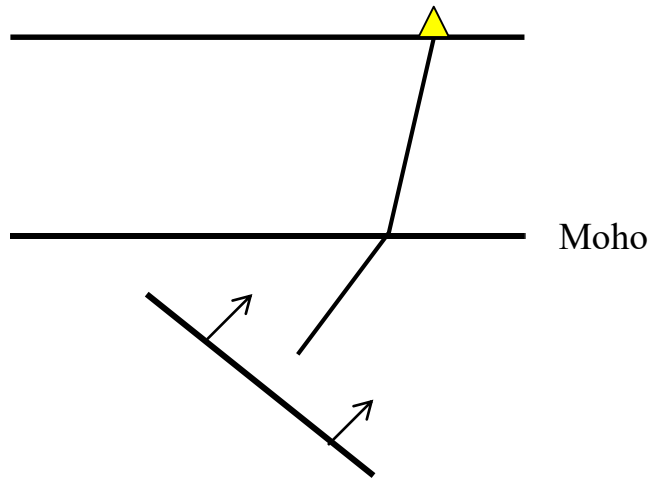
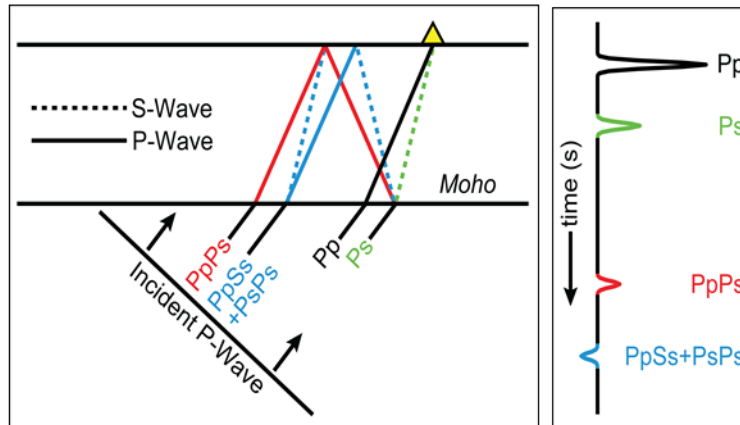
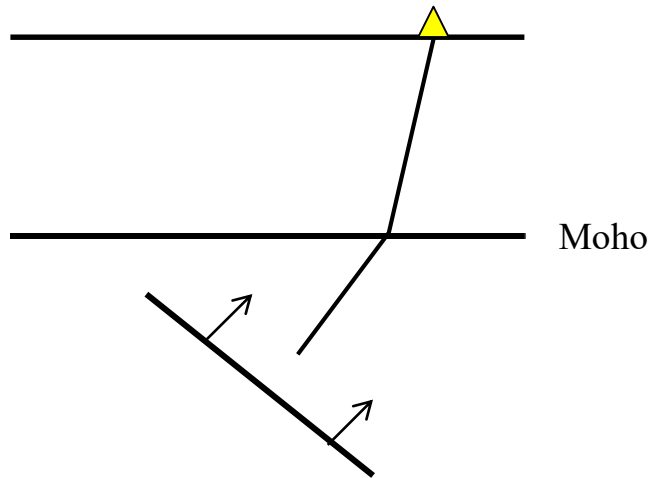


Figure 6.3-7: Diagram of the receiver function approach.

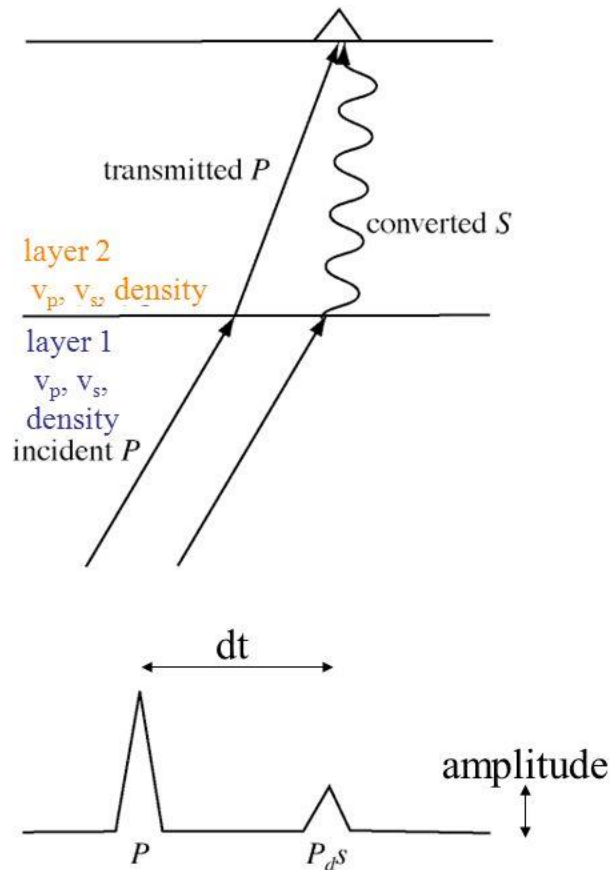




Reverberations may interfere
with first arrival



Sediments may bring
additional phases



converted pulse:

delay time dt depends on depth of interface and v_p, v_s of top layer

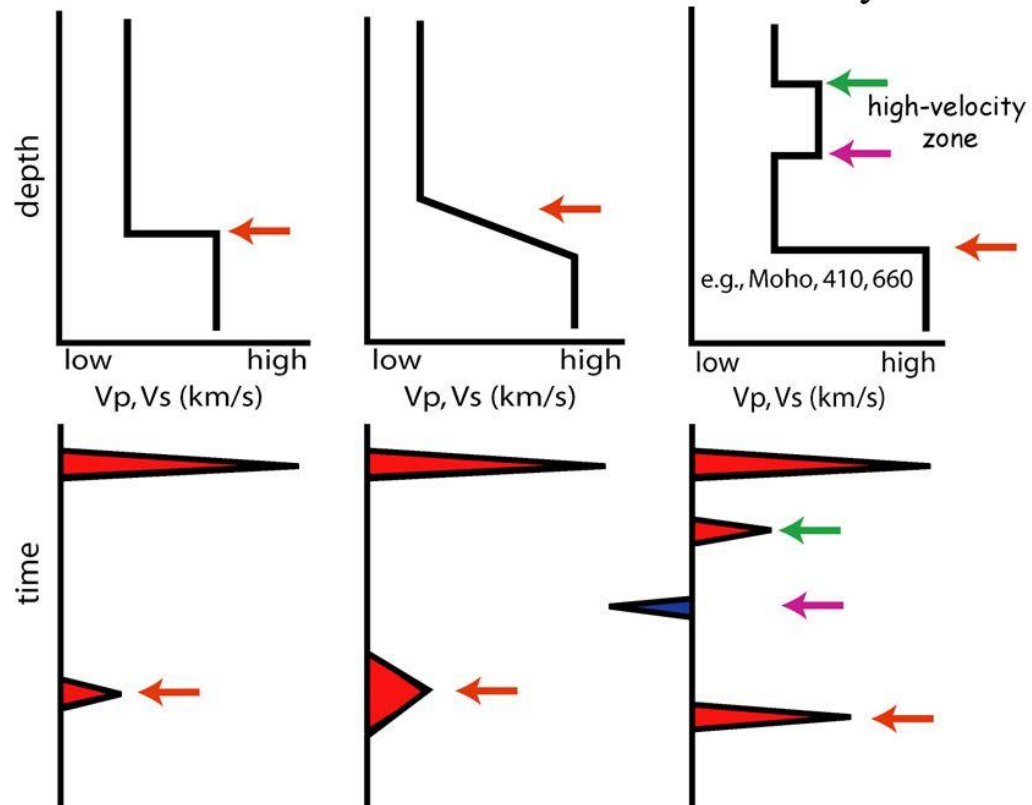
amplitude depends on velocity contrast (mostly) and density contrast (weakly) at the interface

converted arrival:

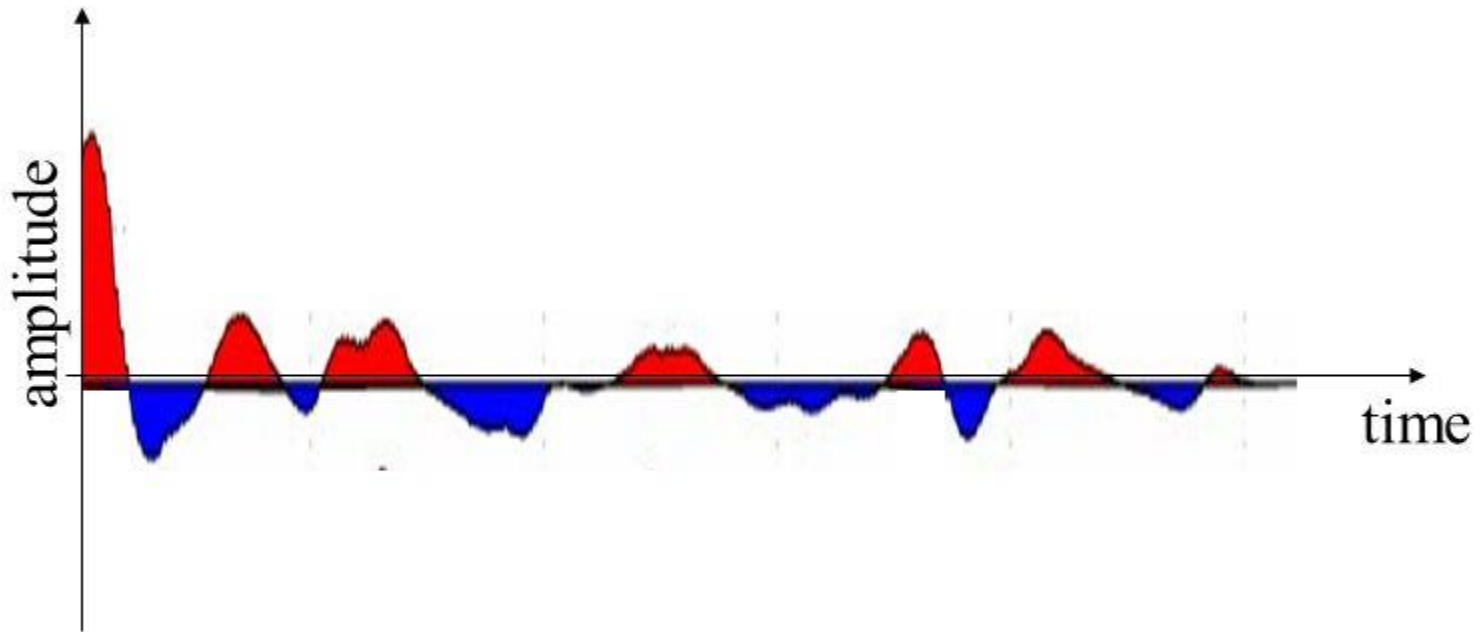
"+" bump = bottom slow, top fast

"-" bump = bottom fast, top slow

receiver functions are sensitive to discontinuity structure



A single receiver function - hard to interpret

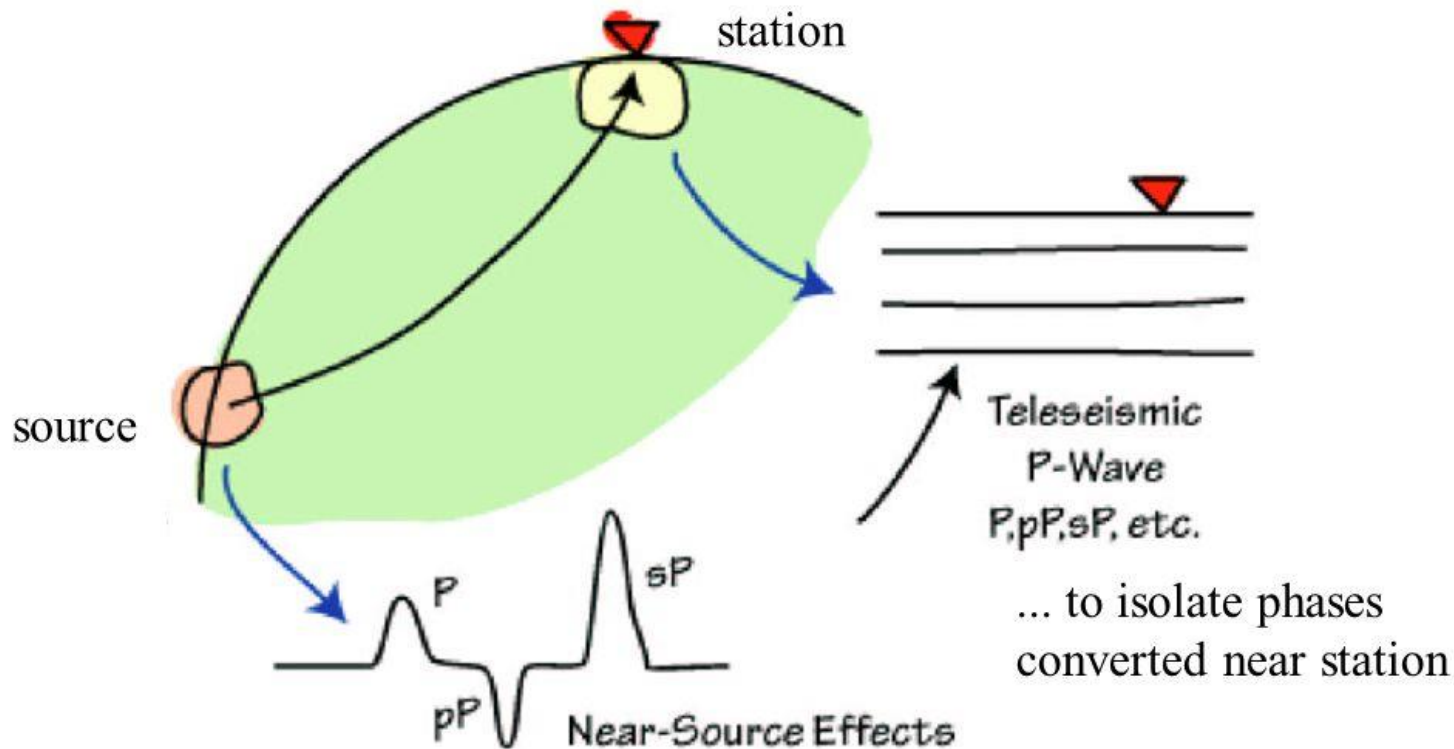


one receiver function per earthquake

-function of slowness (incidence angle)

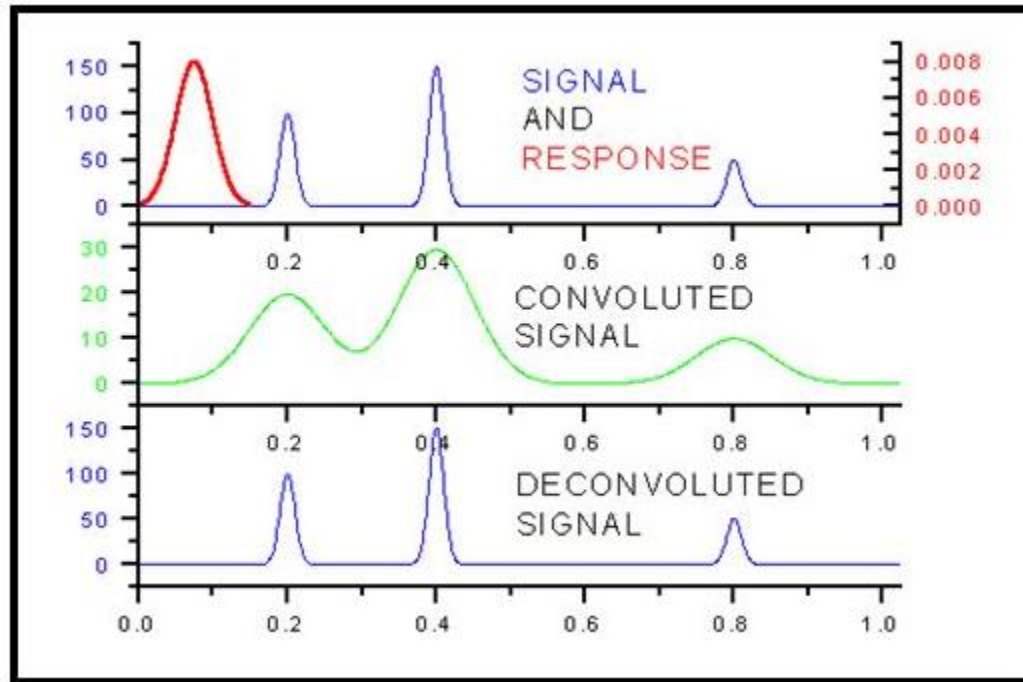
-function of backazimuth (unless flat layered isotropic case)

unfortunately, incident P is not a nice simple bump:

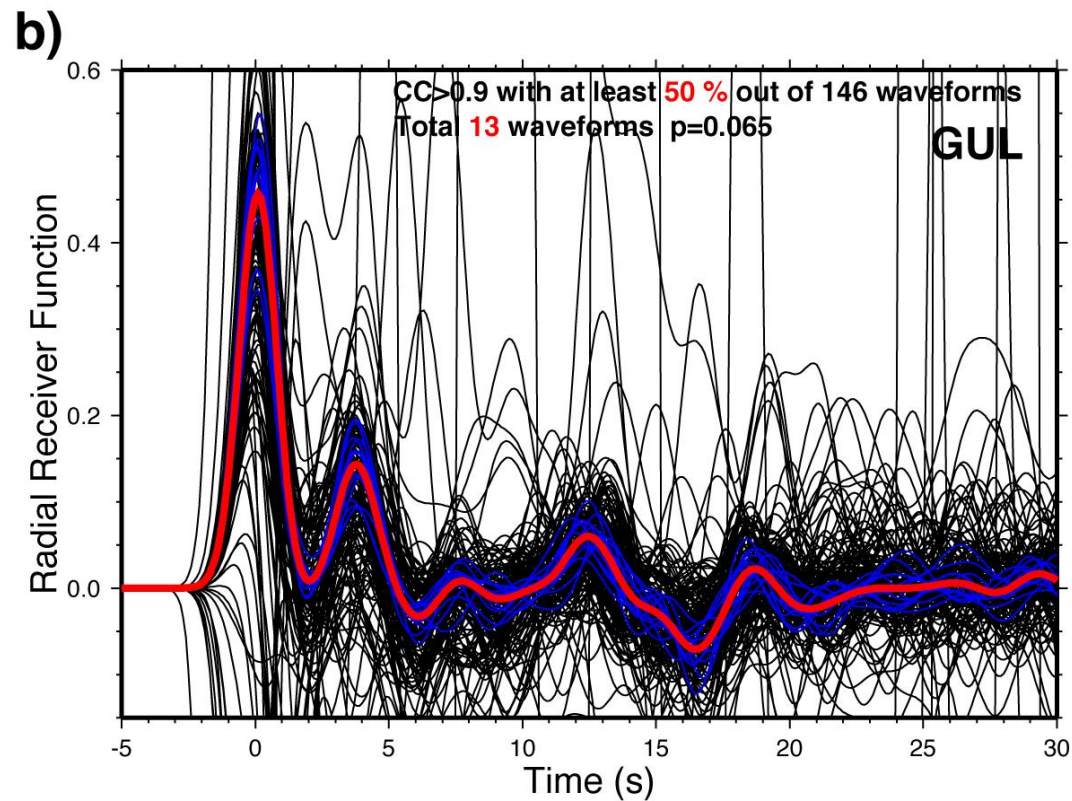


need to remove these bits ...

Deconvolution of the source function

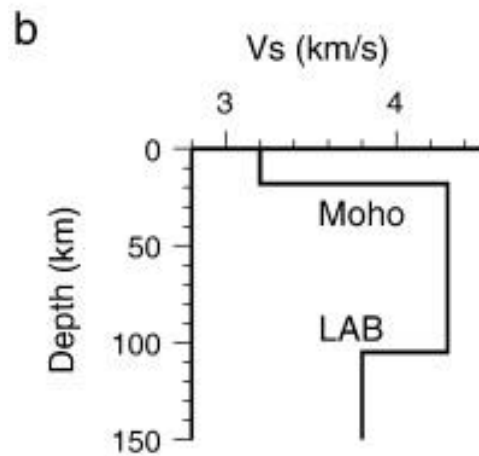


Stack of events: average over azimuth

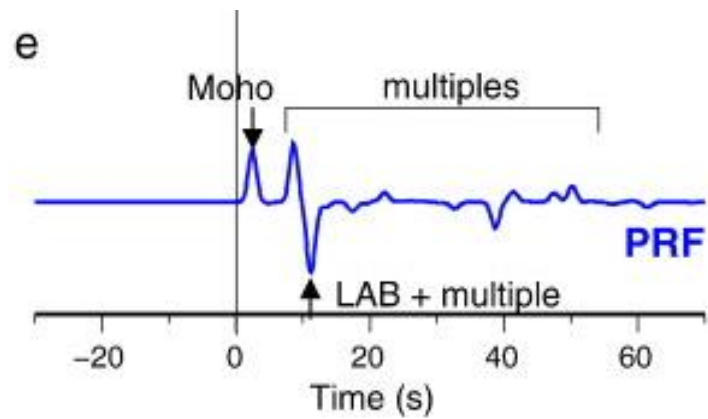
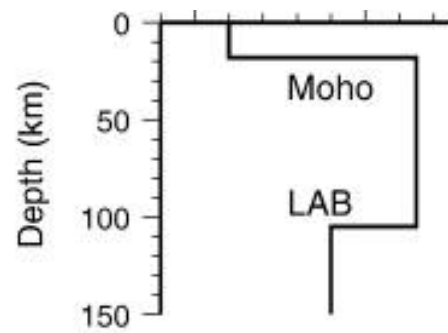


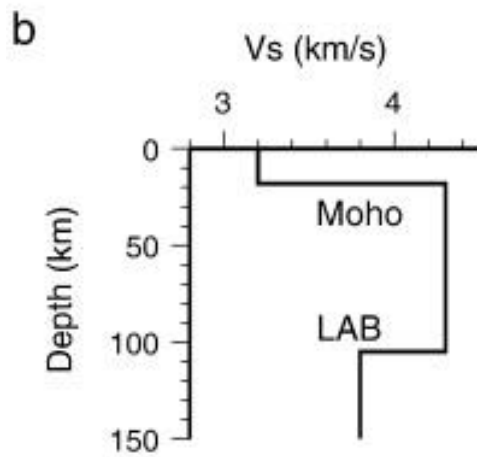
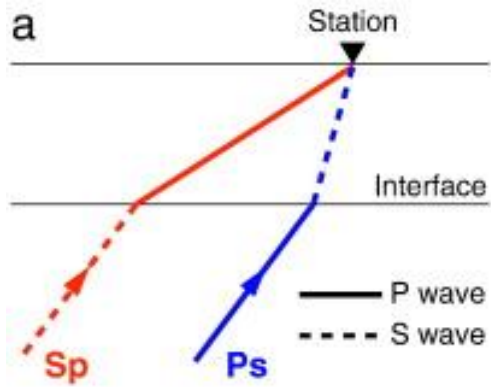
from Tkalcic et al., 2010

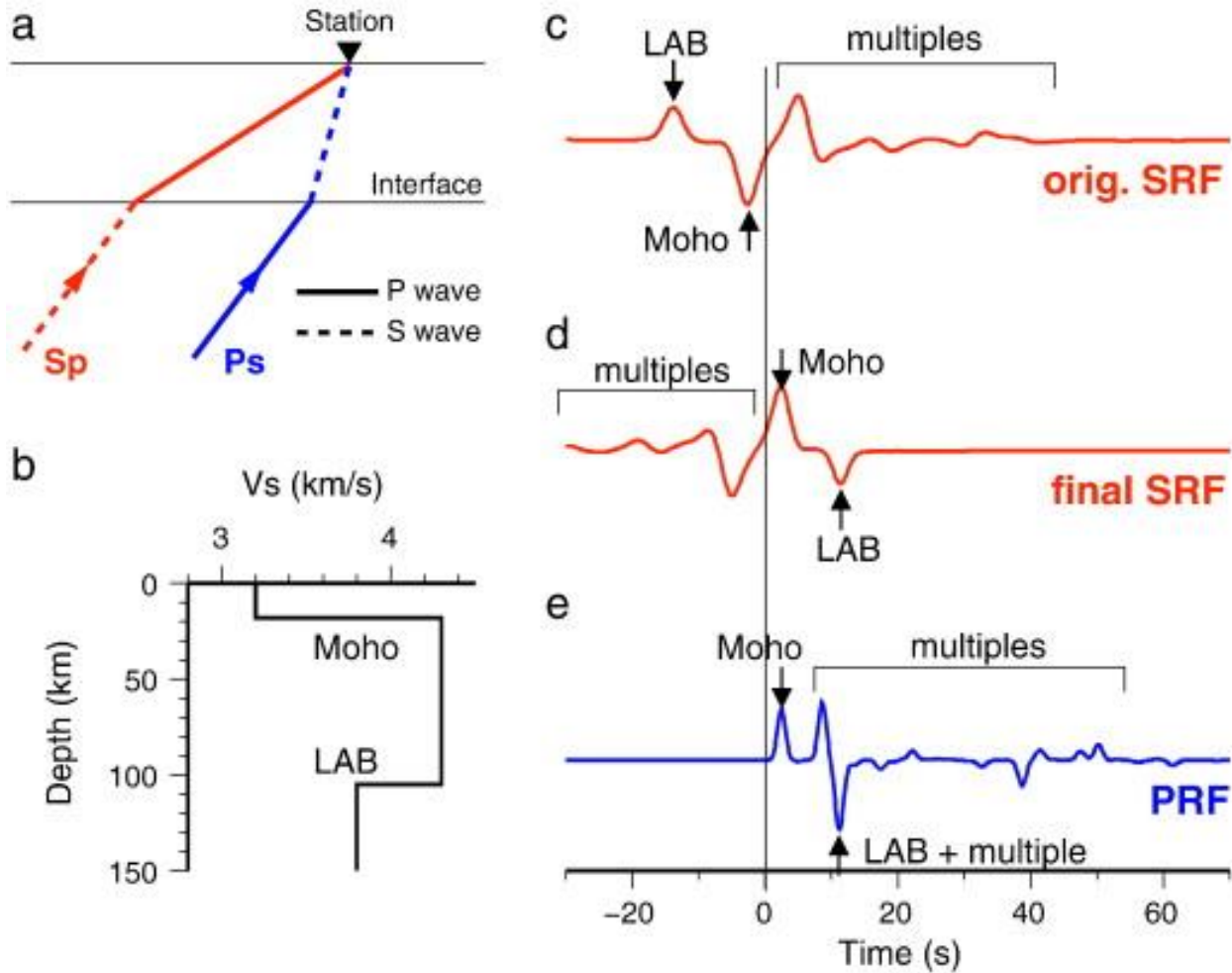
Can RF show a sharp lithosphere-asthenosphere boundary?

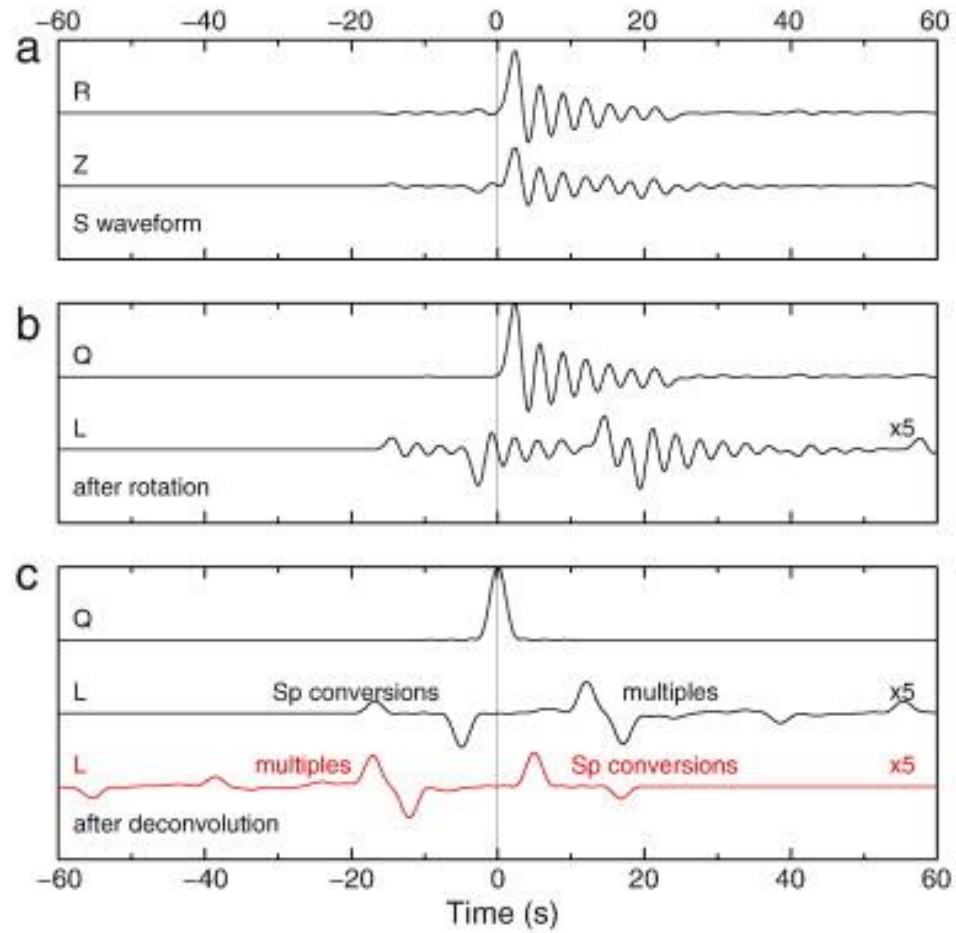


Kind et al., 2012









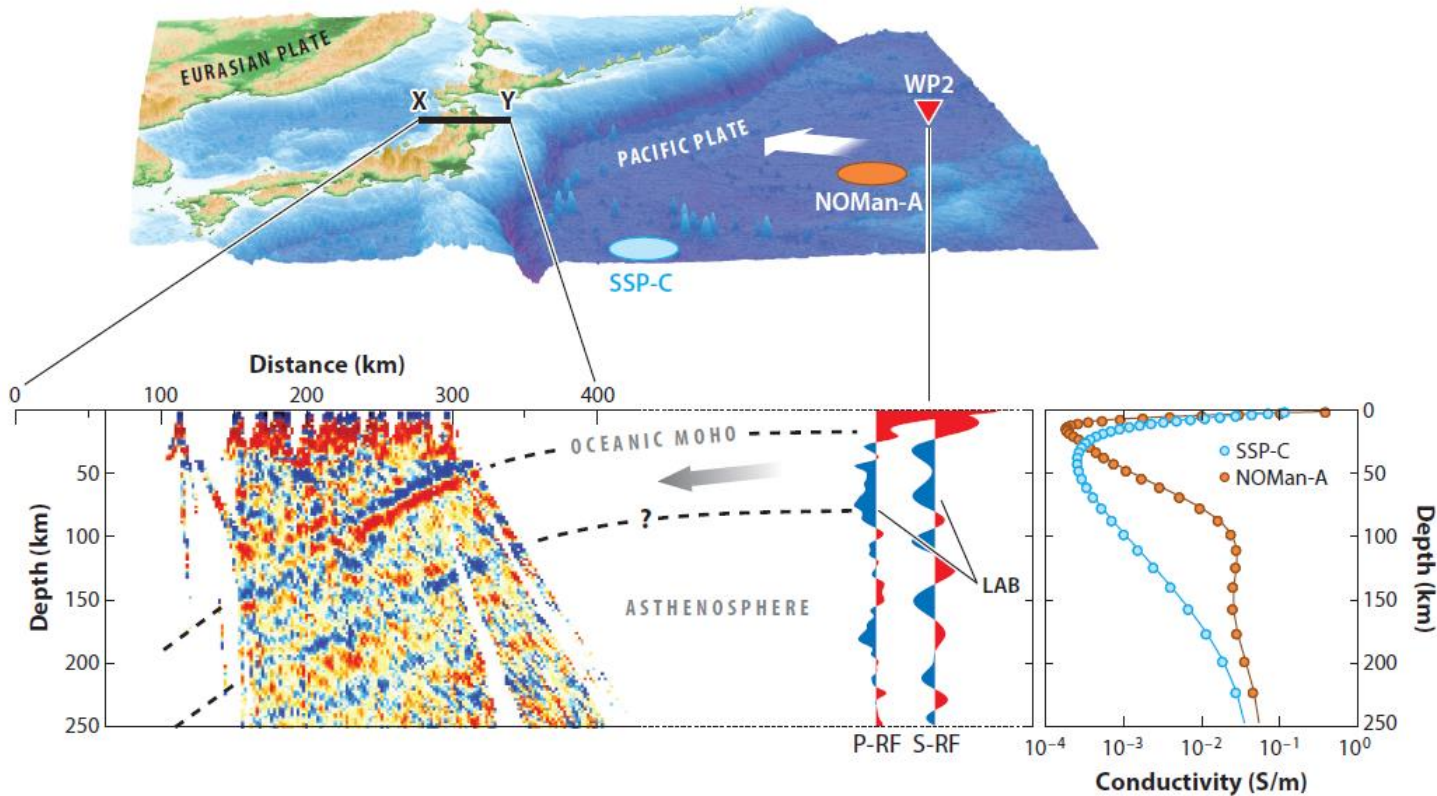
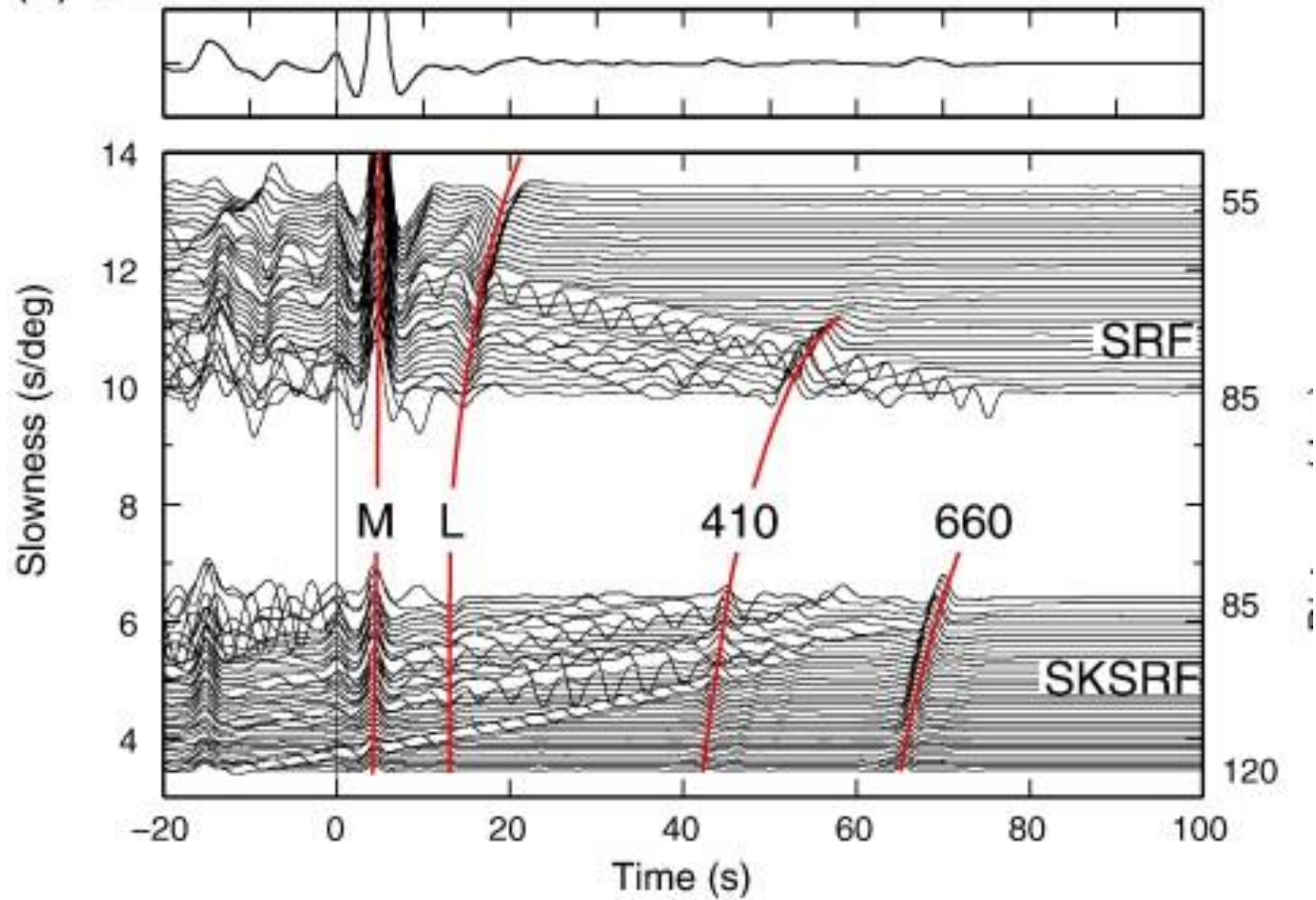
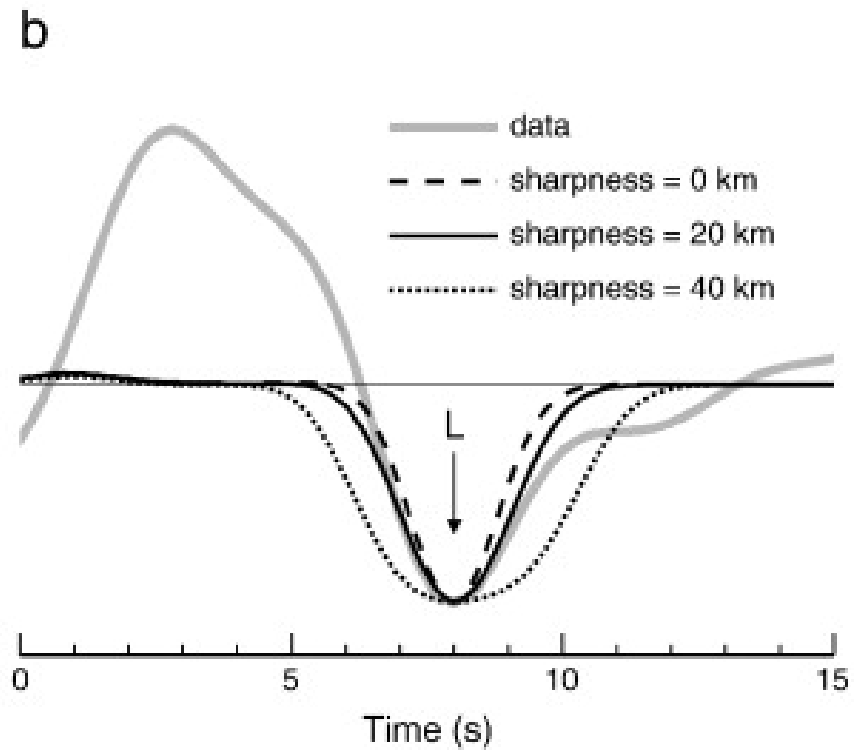
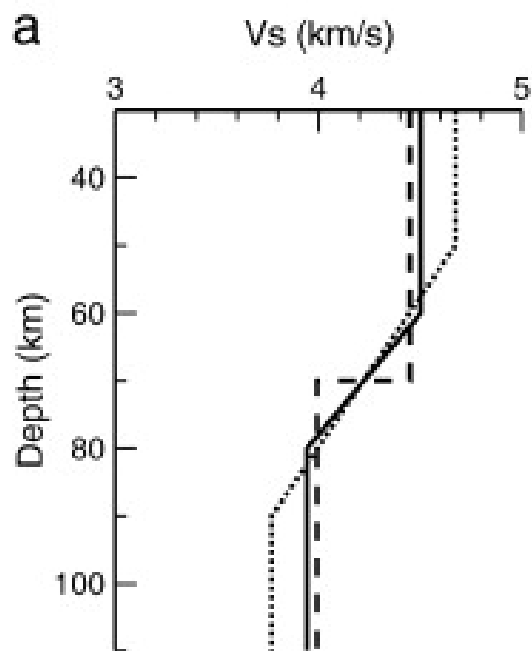


Figure 11

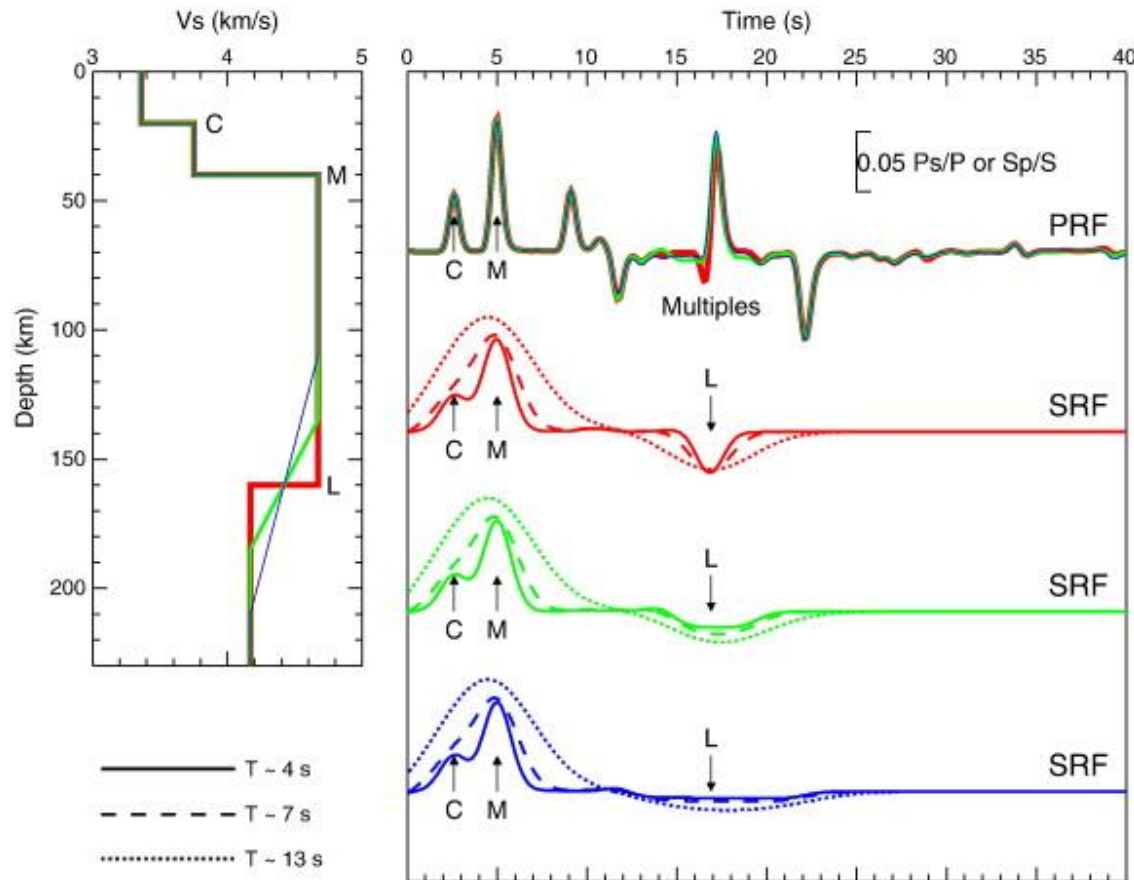
Lithosphere–asthenosphere system at a subduction zone: Shown are a P-RF image using dense land seismic data of Hi-net from Japan and a P-RF and S-RF image for the seafloor borehole station WP2, adapted from Kawakatsu et al. (2009). Also shown are the regional electrical conductivity profiles in two areas, NOMan-A and SSP-C; these data are from Baba et al. (2013). Abbreviations: LAB, lithosphere–asthenosphere boundary; NOMan, Normal Oceanic Mantle Project; P-RF, P-receiver function; S-RF, S-receiver function; SSP, Stagnant Slab Project.

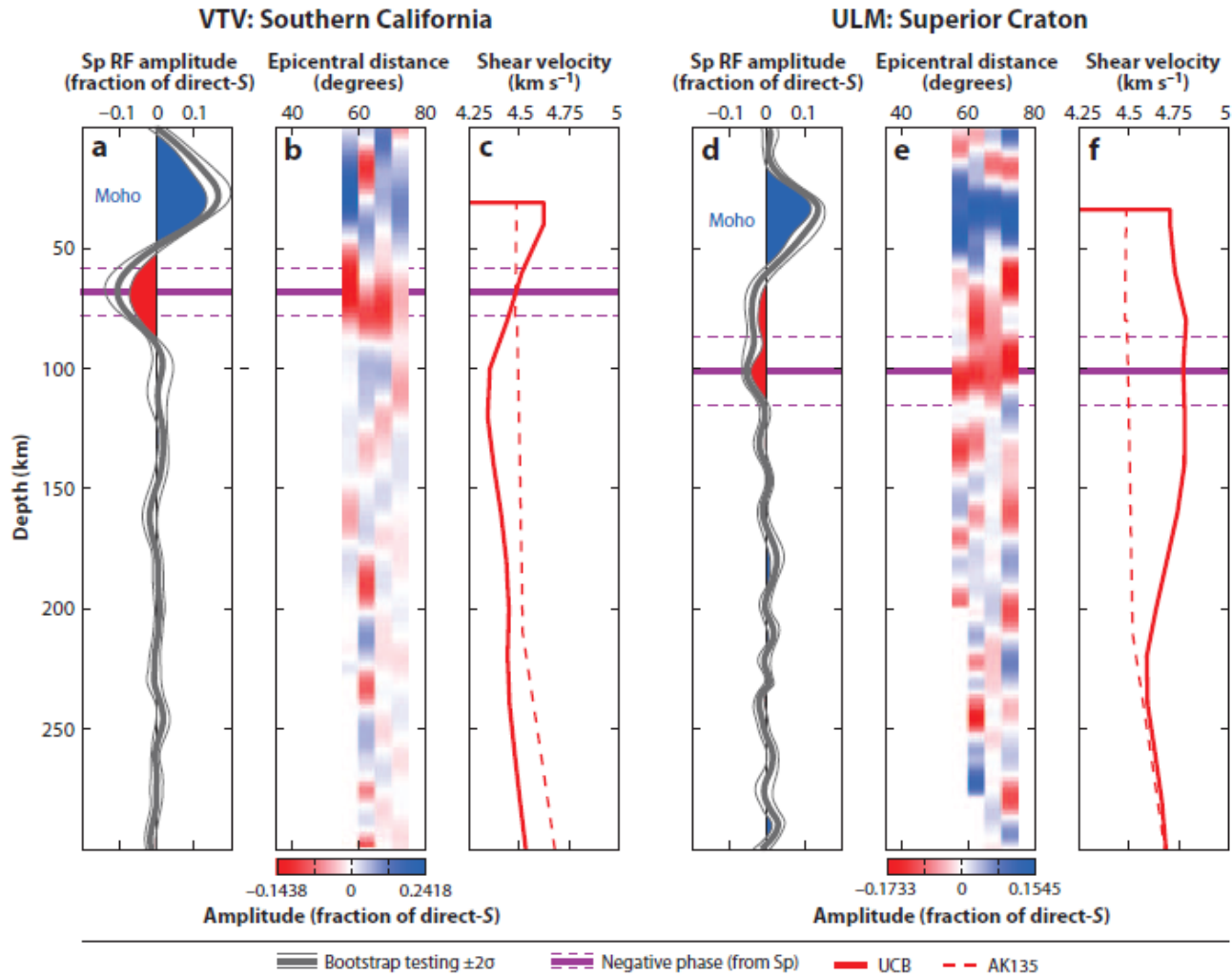
(a) SRF+SKSRF





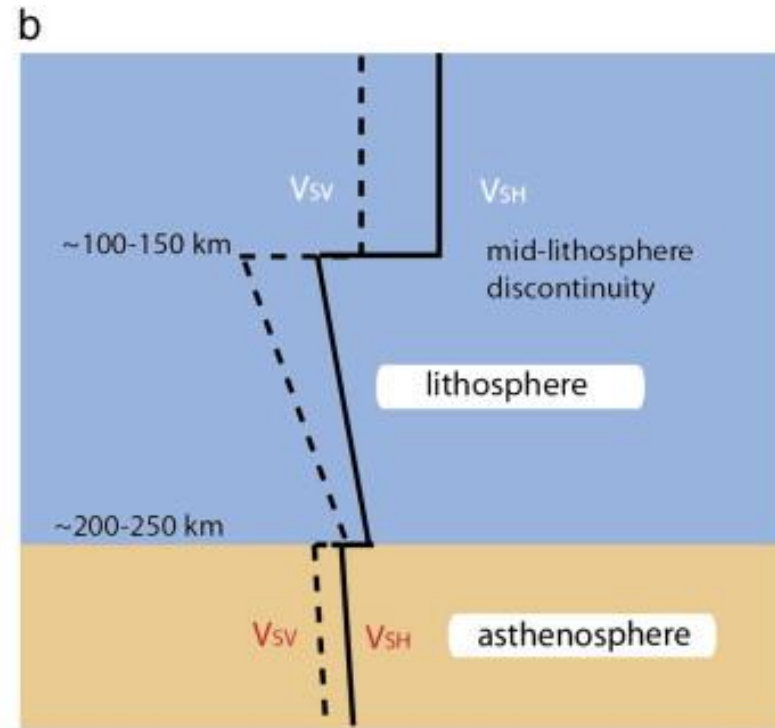
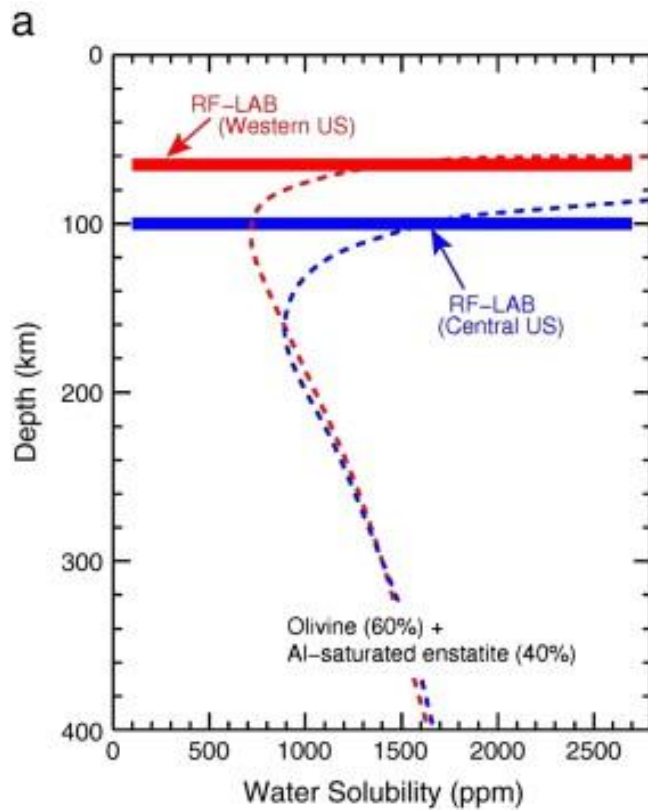
Gradient of the LAB



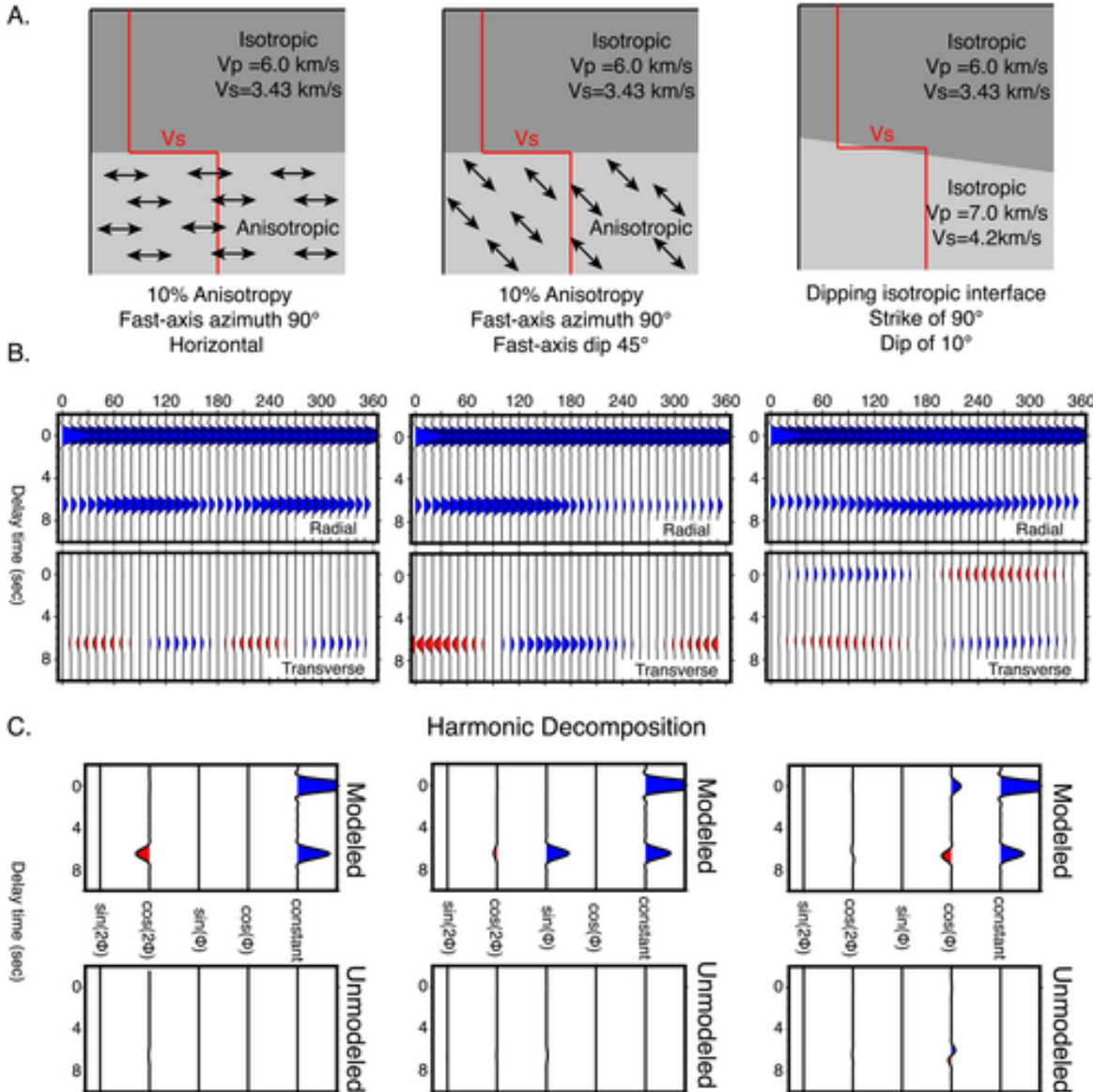


Fischer et al., 2010

LAB or MLD?



Kind et al., 2012



Conclusion

RFs:
important
constraints to
characterize the
LAB

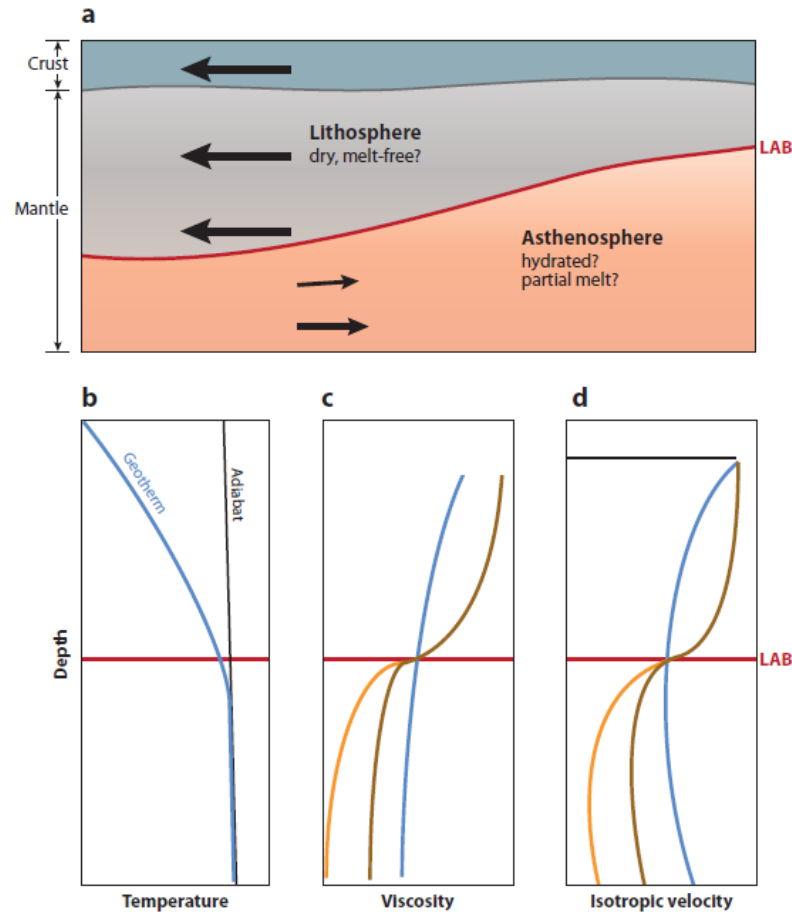


Figure 1

Schematic models of lithosphere-asthenosphere boundary (LAB) properties. (a) Depth profile through the lithosphere and asthenosphere. Arrows show the motion of a coherent lithospheric layer over a deforming asthenosphere. (b) Temperature as a function of depth. In the absence of other factors, the lithosphere would correspond to the cold thermal boundary layer represented by subadiabatic temperatures. (c) Mantle viscosity for three cases. Blue: the geotherm in panel b. Brown: the geotherm superimposed on a compositional difference at the LAB (dry lithosphere over hydrated asthenosphere). Orange: the latter case plus partial melt in the asthenosphere. (d) Isotropic shear velocity corresponding to the three cases in panel c. The black line schematically illustrates the velocity increase from the crust to the mantle.

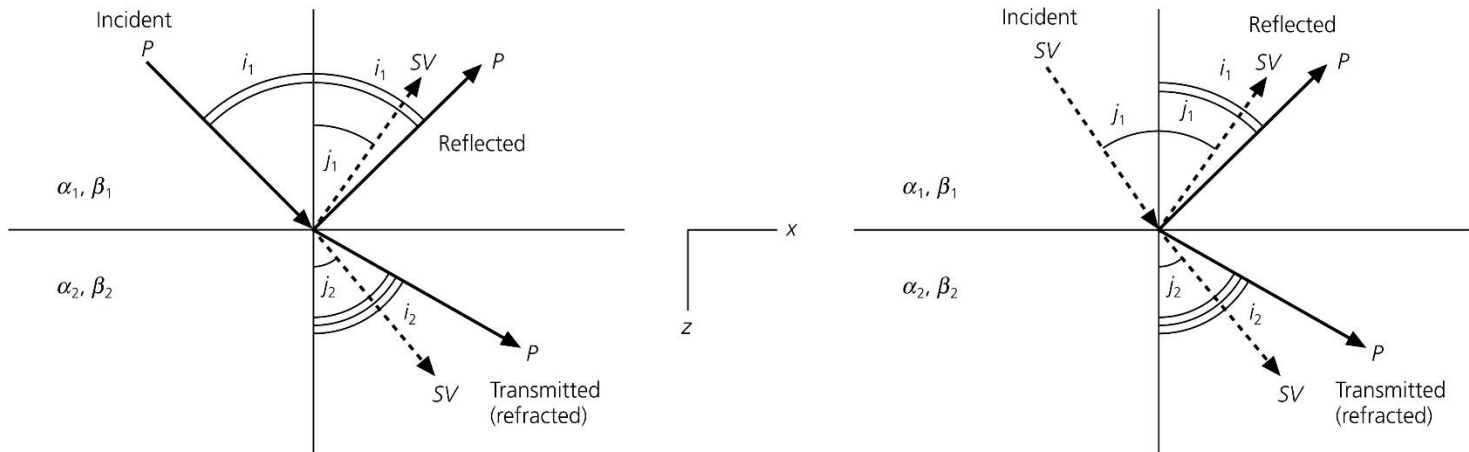


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Figure 2.5-5: Transmitted and reflected waves for incident *P* and *SV* waves.



attempt at a standard moveout plot for narrow azimuthal range

